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## To cite this version:

Simone Naldi, Vincent Neiger. A divide-and-conquer algorithm for computing Gröbner bases of syzygies in finite dimension. 2020. hal-02480240v1

## HAL Id: hal-02480240 https://unilim.hal.science/hal-02480240v1

Preprint submitted on 15 Feb 2020 (v1), last revised 4 Jun 2020 (v2)

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# A divide-and-conquer algorithm for computing Gröbner bases of syzygies in finite dimension 

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#### Abstract

Let $f_{1}, \ldots, f_{m}$ be elements in a quotient $\mathcal{R}^{n} / \mathcal{N}$ which has finite dimension as a $\mathbb{K}$-vector space, where $\mathcal{R}=\mathbb{K}\left[X_{1}, \ldots, X_{r}\right]$ and $\mathcal{N}$ is an $\mathcal{R}$-submodule of $\mathcal{R}^{n}$. We address the problem of computing a Gröbner basis of the module of syzygies of $\left(f_{1}, \ldots, f_{m}\right)$, that is, of vectors $\left(p_{1}, \ldots, p_{m}\right) \in \mathcal{R}^{m}$ such that $p_{1} f_{1}+\cdots+p_{m} f_{m}=0$.

An iterative algorithm for this problem was given by Marinari, Möller, and Mora (1993) using a dual representation of $\mathcal{R}^{n} / \mathcal{N}$ as the kernel of a collection of linear functionals. Following this viewpoint, we design a divide-and-conquer algorithm, which can be interpreted as a generalization to several variables of Beckermann and Labahn's recursive approach for matrix Padé and rational interpolation problems in univariate contexts. To highlight the interest of this method, we focus on the specific case of bivariate Pade approximation and show that it improves upon the best known complexity bounds.


## KEYWORDS

Syzygies; Gröbner basis; Padé approximation; divide and conquer algorithm.

## 1 INTRODUCTION

Context. In what follows, we consider the ring $\mathcal{R}=\mathbb{K}\left[X_{1}, \ldots, X_{r}\right]$ of $r$-variate polynomials over an abstract base field $\mathbb{K}$ and a $\mathcal{R}$ submodule $\mathcal{N} \subset \mathcal{R}^{n}$ such that $\mathcal{R}^{n} / \mathcal{N}$ has finite dimension $D$ as a $\mathbb{K}$-vector space. Then, for a given vector $\left(f_{1}, \ldots, f_{m}\right) \in\left(\mathcal{R}^{n}\right)^{m}$ seen as a matrix $F \in \mathcal{R}^{m \times n}$, this paper studies algorithms for computing a Gröbner basis of the module of syzygies

$$
\operatorname{Syz}_{\mathcal{N}}(F)=\left\{p \in \mathcal{R}^{m} \mid p F \in \mathcal{N}\right\}
$$

where $\boldsymbol{p}$ is seen as a $1 \times m$ row vector. Note that $\mathcal{R}^{m} / \mathrm{Syz}_{\mathcal{N}}(F)$ also has finite dimension, at most $D$, as a $\mathbb{K}$-vector space.

Following a path of work pioneered by Marinari, Möller and Mora [1, 20, 22], we focus on a specific situation where $\mathcal{N}$ is described using duality. That is, $\mathcal{N}$ is known through $D$ linear functionals $\varphi_{j}: \mathcal{R}^{n} \rightarrow \mathbb{K}$ such that $\mathcal{N}=\cap_{1 \leq j \leq D} \operatorname{ker}\left(\varphi_{j}\right)$. In this context, it is customary to make an assumption equivalent to the following: $\mathcal{N}_{i}=\cap_{1 \leq j \leq i} \operatorname{ker}\left(\varphi_{i}\right)$ is a $\mathcal{R}$-module, for $1 \leq i \leq D$; see for example [20, Algo. 2] [13, Eqn. (4.1)] [25, Eqn. (5)] for such assumptions and related algorithms. Namely, this assumption allows one to design iterative algorithms which compute bases of $\mathrm{Syz}_{\mathcal{N}_{i}}(F)$ iteratively for increasing $i$, until reaching $i=D$ and obtaining the sought basis of $\mathrm{Syz}_{\mathcal{N}}(F)$. We remark that [20] focuses on $m=n=1$ and $F=[1]$, in which case $\mathrm{Syz}_{\mathcal{N}_{i}}(F)=\mathcal{N}_{i}$, but the algorithms in that reference directly extend to the case $m \geq 1$ and $\boldsymbol{F} \in \mathcal{R}^{m \times n}$.

Ideal of points and Padé approximation. One particular case of interest is when $\mathcal{N}$ is the vanishing ideal of a given set of points:
$n=1$, and $\mathcal{N}$ is the ideal of all polynomials in $\mathcal{R}$ which vanish at distinct points $\boldsymbol{\alpha}_{1}, \ldots, \boldsymbol{\alpha}_{D} \in \mathbb{K}^{r}$. Here, one takes the linear functionals for evaluation: $\varphi_{j}: f \in \mathcal{R} \mapsto f\left(\boldsymbol{\alpha}_{j}\right) \in \mathbb{K}$. The question is, given the points, $m$ polynomials as $F \in \mathcal{R}^{m \times 1}$, and a monomial order $\leqslant$, to compute a $\leqslant$-Gröbner basis of the set of vectors $\boldsymbol{p}$ such that $\boldsymbol{p} \boldsymbol{F}$ vanishes at all the points. When $m=1$ and $\boldsymbol{F}=[1]$, this means computing a $\leqslant$-Gröbner basis of the ideal of the points, as studied in [20, 21].

Another case is that of (multivariate) Padé approximation and its extensions, as studied in [12-14, 25], as well as in [6] in the context of the computation of multidimensional linear recurrence relations. The basic setting is for $n=1$, with $\mathcal{N}$ an ideal of the form $\left\langle X_{1}^{d_{1}}, \ldots, X_{r}^{d_{r}}\right\rangle$, and $F=\left[{ }_{-1}^{f}\right]$ for some given $f \in \mathcal{R}$. Then, elements of $\mathrm{Syz}_{\mathcal{N}}(\boldsymbol{F})$ are vectors $(q, p) \in \mathcal{R}^{2}$ such that $f=p / q \bmod$ $X_{1}^{d_{1}}, \ldots, X_{r}^{d_{r}}$. Here, the $D=d_{1} \cdots d_{r}$ linear functionals correspond to the coefficients of multidegree less than $\left(d_{1}, \ldots, d_{r}\right)$; note that not all orderings of these functionals satisfy the assumption above.
For these two situations, as well as some extensions of them, the fastest known algorithms rely on linear algebra and have a cost bound of $O\left(m D^{2}+r D^{3}\right)$ operations in $\mathbb{K}[13,20]$; this was recently improved in [23, Thm. 2.13] and [24] to $O\left(m D^{\omega-1}+r D^{\omega} \log (D)\right)$ where $\omega<2.38$ is the exponent of matrix multiplication $[8,19]$.

The univariate case. This problem has received attention in the case of a single variable ( $r=1$ ) notably thanks to the numerous applications of Hermite-Padé approximation and matrix rational interpolation, which are the two situations described above. Iterative algorithms were given in $[2,4,28]$ and can be seen as univariate analogues of [20, Algo. 2] and [13, Algo. 4.7].

A breakthrough divide and conquer approach was designed by Beckermann and Labahn in [3, Algo. SPHPS], allowing one to take advantage of univariate polynomial matrix multiplication while previous iterative algorithms only relied on naive linear algebra operations. This led to a line of work [15-17, 27, 29] which consistently improved the incorporation of fast linear algebra and fast polynomial multiplication in this divide and conquer framework, culminating in cost bounds for rational interpolation and HermitePadé approximation which are close asymptotically to the size of the problem (if $\omega=2$, these cost bounds are quasi-linear in the size of the input instance). To the best of our knowledge, no similar divide and conquer technique has been developed in multivariate settings.

Contribution. We propose a divide and conquer algorithm for the problem of computing a $\leqslant$-Gröbner basis of $\operatorname{Syz}_{\mathcal{N}}(F)$ in the multivariate case. This is based on the iterative algorithms in [13, 20], observing that each step of the iteration can be interpreted as a left multiplication by a matrix which has a specific shape, which we call elementary Gröbner basis (see Section 3). The new algorithm
reorganizes these matrix products through a divide and conquer strategy, and thus groups several products by elementary Gröbner bases into a single multivariate polynomial matrix multiplication.

To illustrate the interest of this new approach, we specialize it to multivariate matrix Padé approximation and derive complexity bounds for this case. We obtain the next result, which is a particular case of Proposition 5.5.

Theorem 1.1. For $\mathcal{R}=\mathbb{K}[X, Y]$, let $f_{1}, \ldots, f_{m} \in \mathcal{R}$, and let $\leqslant$ be a monomial order on $\mathcal{R}$. Then one can compute a minimal $\leqslant-G r o ̈ b n e r ~$ basis of the module of Hermite-Padé approximants

$$
\left\{\left(p_{1}, \ldots, p_{m}\right) \in \mathcal{R}^{m} \mid p_{1} f_{1}+\cdots+p_{m} f_{m}=0 \bmod \left\langle X^{d}, Y^{d}\right\rangle\right\}
$$

using $O^{\sim}\left(m^{\omega} d^{\omega+2}\right)$ operations in $\mathbb{K}$, where $O^{\sim}(\cdot)$ means that polylogarithmic factors are omitted.

In this case the vector space dimension is $D=d^{2}$. Thus, as noted above and to the best of our knowledge, the fastest previously known algorithm for this task has a cost of $O^{\sim}\left(m d^{2(\omega-1)}+d^{2 \omega}\right)$ operations in $\mathbb{K}$ and does not exploit fast polynomial multiplication.

Perspectives. The base case of our divide and conquer algorithm concerns the case $\mathcal{N}=\operatorname{ker}(\varphi)$ of a single linear functional, detailed in Section 3; we thus work in a vector space $\mathcal{R}^{n} / \mathcal{N}$ of dimension 1. A natural perspective is to improve the efficiency of our algorithm thanks to a better exploitation of fast linear algebra by grouping several base cases together; using fast linear algebra to accelerate the base case was a key strategy in obtaining efficient univariate algorithms [15, 17]. In the context of Padé approximation, where one can introduce the variables one after another, one could also try to incorporate known algorithms for the univariate case

One reason why these improvements are not straightforward to do in the multivariate case is that there is no direct generalization of a property at the core of the correctness of univariate algorithms. This property (see [18, Lem. 2.4]) states that if $\boldsymbol{P}_{1}$ is a $\leqslant_{1}$-Gröbner basis of $\mathcal{N}_{1} \supset \mathcal{N}$ and $\boldsymbol{P}_{2}$ is a $\leqslant_{2}$-Gröbner basis of $\mathrm{Syz}_{\mathcal{N}}\left(\boldsymbol{P}_{1}\right)$, then $P_{2} P_{1}$ is a $\leqslant_{1}$-Gröbner basis of $\mathcal{N}$, provided that the order $\leqslant_{2}$ is well chosen (a Schreyer order for $\boldsymbol{P}_{1}$ and $\leqslant_{1}$, see Section 2.4). We give a counterexample to such a property in Example 3.6. It remains open to find a similar general property that would help to design algorithms based on matrix multiplication in the multivariate case.

Another difficulty arises in analyzing the complexity of our divide and conquer scheme in contexts where the number of elements in the sought Gröbner basis is not well controlled, such as rational interpolation. Indeed, this number corresponds to the size of the matrices manipulated in the algorithm, and therefore is directly related to the cost of the matrix multiplication. In fact, the worst-case number of elements is often very pessimistic compared to what is observed in a generic situation, and also depends on the monomial order. Therefore future work involves investigating complexity bounds for generic input.

## 2 PRELIMINARIES

### 2.1 Notation

Here and hereafter, the coordinate vector with 1 at index $i$ is denoted by $\boldsymbol{e}_{i}$; its dimension is inferred from the context. A monomial in $\mathcal{R}^{m}$ is an element of the form $v \boldsymbol{e}_{i}$ for some $1 \leq i \leq m$ and some monomial $v$ in $\mathcal{R} ; i$ is called the support of $v \boldsymbol{e}_{i}$. We denote by
$\operatorname{Mon}\left(\mathcal{R}^{m}\right)$ the set of all monomials in $\mathcal{R}^{m}$. A term is a monomial multiplied by a nonzero constant from $\mathbb{K}$. The elements of $\mathcal{R}^{m}$ are $\mathbb{K}$-linear combinations of monomials in $\operatorname{Mon}\left(\mathcal{R}^{m}\right)$ and are called polynomials.
Elements in $\mathcal{R}$ are written in regular font (e.g. monomials $\mu$ and $v$ and polynomials $f$ and $p$ ), while elements in $\mathcal{R}^{m}$ are boldfaced (e.g. monomials $\boldsymbol{\mu}$ and $\boldsymbol{v}$ and polynomials $f$ and $\boldsymbol{p}$ ). Vectors or (ordered) lists of polynomials in $\mathcal{R}^{m}$ are seen as matrices, written in boldfaced capital letters; precisely, $\left(\boldsymbol{p}_{1}, \ldots, \boldsymbol{p}_{k}\right) \in\left(\mathcal{R}^{m}\right)^{k}$ is seen as a matrix $\boldsymbol{P} \in \mathcal{R}^{k \times m}$ whose $i$ th row is $\boldsymbol{p}_{i}$. In particular, in what follows the default orientation is to see an element of $\mathcal{R}^{m}$ as a row vector in $\mathcal{R}^{1 \times m}$.

For the sake of completeness, we recall below in Sections 2.2 to 2.4 some classical definitions from commutative algebra concerning submodules of $\mathcal{R}^{m}$; we assume familiarity with the corresponding notions concerning ideals of $\mathcal{R}$. For a more detailed introduction the reader may refer to [9-11].

### 2.2 Monomial orders for modules

A monomial order on $\mathcal{R}^{m}$ is a total order $\leqslant$ on $\operatorname{Mon}\left(\mathcal{R}^{m}\right)$ such that, for $v \in \operatorname{Mon}(\mathcal{R})$ and $\boldsymbol{\mu}_{1}, \boldsymbol{\mu}_{2} \in \operatorname{Mon}\left(\mathcal{R}^{m}\right)$ with $\boldsymbol{\mu}_{1} \leqslant \boldsymbol{\mu}_{2}$, one has $\boldsymbol{\mu}_{1} \leqslant v \boldsymbol{\mu}_{1} \leqslant v \boldsymbol{\mu}_{2}$; hereafter $\boldsymbol{\mu}_{1} \prec \boldsymbol{\mu}_{2}$ means that $\boldsymbol{\mu}_{1} \leqslant \boldsymbol{\mu}_{2}$ and $\boldsymbol{\mu}_{1} \neq \boldsymbol{\mu}_{2}$. For $\boldsymbol{p} \in \mathcal{R}^{m}$, its $\leqslant$-leading monomial is denoted by $\operatorname{lm}_{\S}(\boldsymbol{p})$ and is the largest of its monomials with respect to the order $\leqslant$ (we take the convention $\operatorname{lm}_{\S}(0)=0$ for $0 \in \mathcal{R}^{n}$ the zero element). We extend this notation to collections of polynomials $\mathcal{P} \subset \mathcal{R}^{m}$ with $\operatorname{lm}_{\S}(\mathcal{P})=\left\{\operatorname{lm}_{\preccurlyeq}(\boldsymbol{p}): \boldsymbol{p} \in \mathcal{P}\right\}$, and to matrices $P \in \mathcal{R}^{k \times m}$ with $\operatorname{lm}_{\S}(P)$ the $k \times m$ matrix whose $i$ th row is the $\leqslant$-leading monomial of the $i$ th row of $\boldsymbol{P}$.

Example 2.1. The usual lexicographic comparison is a monomial order on $\mathbb{K}[X, Y]: X^{a} Y^{b} \leqslant_{\text {lex }} X^{a^{\prime}} Y^{b^{\prime}}$ if and only if $a<a^{\prime}$ or ( $a=$ $a^{\prime}$ and $b<b^{\prime}$ ). It can be used to define a monomial order on $\mathbb{K}[X, Y]^{2}$, called the term-over-position lexicographic order: for $\mu, v$ in $\operatorname{Mon}(\mathbb{K}[X, Y])$ and $i, j$ in $\{1,2\}, \mu \boldsymbol{e}_{i} \preccurlyeq_{\text {lex }}^{\text {top }} v \boldsymbol{e}_{j}$ if and only if $\mu \preccurlyeq_{\text {lex }} v$ or ( $\mu=v$ and $i<j$ ).

We refer to [9, Sec. 1.§2 and 5.§2] for other classical monomial orders, such as the degree reverse lexicographical order on $\mathcal{R}$, and the construction of term-over-position and position-over-term orders on $\mathcal{R}^{m}$ from orders on $\mathcal{R}$.
A monomial order $\leqslant$ on $\mathcal{R}^{m}$ induces a monomial order $\leqslant_{i}$ on $\mathcal{R}$ for each $1 \leq i \leq m$, by restricting to the $i$ th coordinate: for $v_{1}, v_{2} \in \operatorname{Mon}(\mathcal{R}), v_{1} \preccurlyeq_{i} v_{2}$ if and only if $v_{1} \boldsymbol{e}_{i} \leqslant v_{2} \boldsymbol{e}_{i}$. In particular, $\operatorname{lm}_{\S}(q \boldsymbol{p})$ is a multiple of $\operatorname{lm}_{\S}(\boldsymbol{p})$ for $q \in \mathcal{R}$ and $\boldsymbol{p} \in \mathcal{R}^{m}$ :

Lemma 2.2. Let $\bar{\imath}$ be the support of $\operatorname{lm}_{\S}(\boldsymbol{p})$. Then $\operatorname{lm}_{\S}(q \boldsymbol{p})=$ $\operatorname{lm}_{\leqslant_{\imath}}(q) \operatorname{lm}_{\leqslant}(\boldsymbol{p})$.

Proof. Write $q=\sum_{\ell} v_{\ell}$ and $\boldsymbol{p}=\sum_{i, j} \mu_{i j} \boldsymbol{e}_{i}$ for terms $\mu_{i j}, v_{\ell}$ in $\mathcal{R}$. Then $q \boldsymbol{p}=\sum_{\ell, i, j} v_{\ell} \mu_{i j} \boldsymbol{e}_{i}$, i.e. the terms of $q \boldsymbol{p}$ are all those of the form $v_{\ell} \mu_{i j} \boldsymbol{e}_{i}$. Now let $\bar{\ell}$ and $\bar{j}$ be such that $\mathrm{lm}_{\leqslant_{i}}(q)=v_{\bar{\ell}}$ and $\operatorname{lm}_{\lessgtr}(\boldsymbol{p})=\mu_{\bar{\jmath}} \boldsymbol{e}_{\bar{\imath}}$. Then $v_{\ell}<_{\bar{l}} v_{\bar{\ell}}$ for all $\ell \neq \bar{\ell}$, which implies that $v_{\ell} \mu_{\bar{i} \bar{j}}<_{i} v_{\bar{\ell}} \mu_{\bar{l} \bar{\jmath}}$ and thus, by definition of $\leqslant_{\bar{\imath}}$, that $v_{\ell} \mu_{\bar{i} \bar{j}} \boldsymbol{e}_{\bar{i}}<v_{\bar{\ell}} \mu_{\bar{i} \bar{\jmath}} \boldsymbol{e}_{\bar{i}}$. On the other hand, $\mu_{i j} \boldsymbol{e}_{i}<\mu_{\bar{i} \bar{\jmath}} \boldsymbol{e}_{\bar{i}}$ holds for all $(i, j) \neq(\bar{i}, \bar{j})$, hence $v_{\ell} \mu_{i j} \boldsymbol{e}_{i}<v_{\ell} \mu_{\bar{\jmath} \bar{\jmath}} \boldsymbol{e}_{\bar{\imath}}$. Therefore we obtain $v_{\ell} \mu_{i j} \boldsymbol{e}_{i} \leqslant v_{\bar{\ell}} \mu_{\bar{\imath} \bar{j}} \boldsymbol{e}_{\bar{\imath}}$ for all $(i, j, \ell)$, with equality only if $(i, j, \ell)=(\bar{i}, \bar{\jmath}, \bar{\ell})$. This proves that $\operatorname{lm}_{\S}(q \boldsymbol{p})=v_{\bar{\ell}} \mu_{\bar{\jmath} \bar{j}} \boldsymbol{e}_{\bar{\imath}}=\operatorname{lm}_{\nwarrow_{\imath}}(q) \operatorname{lm}_{\S}(\boldsymbol{p})$.

### 2.3 Gröbner bases

As a consequence of Hilbert's Basis Theorem, any $\mathcal{R}$-submodule of $\mathcal{R}^{m}$ is finitely generated [11, Prop. 1.4]. For a (possibly infinite) collection of polynomials $\mathcal{P} \subset \mathcal{R}^{m}$, we denote by $\langle\mathcal{P}\rangle$ the $\mathcal{R}$-submodule of $\mathcal{R}^{m}$ generated by the elements of $\mathcal{P}$. Similarly, for a matrix $P$ in $\mathcal{R}^{k \times m},\langle\boldsymbol{P}\rangle$ stands for the $\mathcal{R}$-submodule of $\mathcal{R}^{m}$ generated by its rows, that is, $\langle\boldsymbol{P}\rangle=\left\{\boldsymbol{q} \boldsymbol{P} \mid \boldsymbol{q} \in \mathcal{R}^{k}\right\}$.

For a given submodule $\mathcal{M} \subset \mathcal{R}^{m}$, the $\leqslant$-leading module of $\mathcal{M}$ is the module $\left\langle\operatorname{lm}_{\S}(\mathcal{M})\right\rangle$ generated by the leading monomials of the elements of $\mathcal{M}$. Then, a matrix $\boldsymbol{P}$ in $\mathcal{R}^{k \times m}$ whose rows are in $\mathcal{M}$ is said to be a $\leqslant$-Gröbner basis of $\mathcal{M}$ if

$$
\left\langle\operatorname{lm}_{\S}(\mathcal{M})\right\rangle=\left\langle\operatorname{lm}_{\S}(P)\right\rangle
$$

In this case we have $\langle\boldsymbol{P}\rangle=\mathcal{M}$ (see [9, Ch.5, Prop.2.7]), hence we will often omit the reference to the ambient module $\mathcal{M}$ and just say that $P$ is a $\leqslant$-Gröbner basis.

A $\leqslant$-Gröbner basis $\boldsymbol{P}$, whose rows are $\left(\boldsymbol{p}_{1}, \ldots, \boldsymbol{p}_{k}\right)$, is said to be minimal if $\operatorname{lm}_{\preccurlyeq}\left(\boldsymbol{p}_{i}\right)$ is not divisible by $\operatorname{lm}_{\leqslant}\left(\boldsymbol{p}_{j}\right)$, for any $j \neq i$. It is said to be reduced if it is minimal and, for all $1 \leq i \leq k, \operatorname{lm}_{\lessgtr}\left(\boldsymbol{p}_{i}\right)$ is monic and none of the terms of $\boldsymbol{p}_{i}$ is divisible by any of $\left\{\operatorname{lm}_{\preccurlyeq}\left(\boldsymbol{p}_{j}\right) \mid j \neq i\right\}$. Given a monomial order $\leqslant$ and a $\mathcal{R}$-submodule $\mathcal{M} \subset \mathcal{R}^{m}$, there is a reduced $\preccurlyeq$-Gröbner basis of $\mathcal{M}$ and it is unique (up to permutation of its elements) [11, Sec. 15.2].

Example 2.3. The syzygy module

$$
\mathcal{M}=\left\{\left(p_{1}, p_{2}\right) \in \mathbb{K}[X, Y]^{2} \mid p_{1}-p_{2} \in\langle X, Y\rangle\right\}=\operatorname{Syz}_{\langle X, Y\rangle}\left(\left[{ }_{-1}^{1}\right]\right)
$$

is generated by $\left(X \boldsymbol{e}_{1}, Y \boldsymbol{e}_{1}, \boldsymbol{e}_{1}+\boldsymbol{e}_{2}\right)$, that is, by the rows of

$$
\boldsymbol{P}=\left[\begin{array}{cc}
X & 0 \\
Y & 0 \\
1 & 1
\end{array}\right] \in \mathbb{K}[X, Y]^{3 \times 2}
$$

Furthermore, $\boldsymbol{P}$ is the reduced $\stackrel{\text { top }}{{ }_{\text {lex }}}$-Gröbner basis of $\mathcal{M}$.

### 2.4 Schreyer orders

In the context of the computation of bases of syzygies it is generally beneficial to use a specific construction of monomial orders, as first highlighted by Schreyer [26] (see also [11, Th. 15.10] and [5]).

In the univariate case, the notion of shifted degree plays the same role as Schreyer orders and is ubiquitous in the computation of bases of modules of syzygies [15, 16, 29]; an equivalent notion of defects was also used earlier for M-Padé and Hermite-Padé approximation algorithms [2, 3]. Specifically, this provides a monomial order on $\mathcal{R}^{k}$ constructed from a monomial order $\leqslant$ on $\mathcal{R}^{m}$ and from the leading monomials of a $\leqslant$-Gröbner basis in $\mathcal{R}^{m}$ of cardinality $k$.

Definition 2.4. Let $\leqslant$ be a monomial order on $\mathcal{R}^{m}$, and let $L=$ $\left(\boldsymbol{\mu}_{1}, \ldots, \boldsymbol{\mu}_{k}\right)$ be a list of monomials of $\mathcal{R}^{m}$. A Schreyer order for $\leqslant$ and $L$ is any monomial order on $\mathcal{R}^{k}$, denoted by $\leqslant_{L}$, such that for $v_{1} \boldsymbol{e}_{i}, v_{2} \boldsymbol{e}_{j} \in \operatorname{Mon}\left(\mathcal{R}^{k}\right)$, if $v_{1} \boldsymbol{\mu}_{i}<v_{2} \boldsymbol{\mu}_{j}$ then $v_{1} \boldsymbol{e}_{i} \preccurlyeq_{L} v_{2} \boldsymbol{e}_{j}$.
As noted above, we often have $L=\operatorname{lm}_{\S}(P)$ for a list of polynomials $P \in \mathcal{R}^{k \times m}$ (which is typically a $\leqslant-$ Gröbner basis).

Remark that Definition 2.4 uses a strict inequality, and implies that if $v_{1} \boldsymbol{e}_{i} \leqslant{ }_{L} v_{2} \boldsymbol{e}_{j}$, then $v_{1} \boldsymbol{\mu}_{i}<v_{2} \boldsymbol{\mu}_{j}$ or $v_{1} \boldsymbol{\mu}_{i}=v_{2} \boldsymbol{\mu}_{j}$. In particular, for $v_{1}=v_{2}=1$ and assuming $\boldsymbol{\mu}_{i} \neq \boldsymbol{\mu}_{j}$ for all $i \neq j$ (for instance, if $L=\operatorname{lm}_{\preccurlyeq}(P)$ for a minimal $\leqslant$-Gröbner basis $P$ ), then $\boldsymbol{e}_{i} \leqslant_{L} \boldsymbol{e}_{j}$ if and only if $\boldsymbol{\mu}_{i}<\boldsymbol{\mu}_{j}$.

Furthermore, for every $\leqslant$ and $\boldsymbol{L}$, a corresponding Schreyer order exists and can be constructed explicitly: for example, $v_{1} \boldsymbol{e}_{i} \leqslant{ }_{L} v_{2} \boldsymbol{e}_{j}$ if and only if

$$
v_{1} \boldsymbol{\mu}_{i}<v_{2} \boldsymbol{\mu}_{j} \text { or }\left(v_{1} \boldsymbol{\mu}_{i}=v_{2} \boldsymbol{\mu}_{j} \text { and } i<j\right)
$$

This specific Schreyer order is the one used in the algorithms in this paper, where we write

$$
\leqslant_{L} \leftarrow \operatorname{SCHREYERORDER}(\leqslant, L)
$$

to mean that the algorithm constructs it from $\leqslant$ and $L$.

## 3 BASE CASE OF THE DIVIDE AND CONQUER SCHEME

In this section we present the base case of our main algorithm. It constructs Gröbner bases for syzygies modulo the kernel of a single linear functional, which we call elementary and describe in Section 3.1. Further in Section 3.2 we state properties that are useful to prove the correctness of the base case algorithm given in Section 3.3. Precisely, this correctness is written having in mind the design of an algorithm handling several functionals iteratively by repeating this basic procedure and multiplying the elementary bases together.

### 3.1 Elementary Gröbner basis

If $\mathcal{I} \subset \mathcal{R}$ is an ideal such that $\mathcal{R} / \mathcal{I}$ has dimension 1 as a $\mathbb{K}$-vector space, then $I$ is maximal: it is of the form $\left\langle X_{1}-\alpha_{1}, \ldots, X_{r}-\alpha_{r}\right\rangle$ for some point $\left(\alpha_{1}, \ldots, \alpha_{r}\right) \in \mathbb{K}^{r}$, which directly yields the reduced Gröbner basis of $\mathcal{I}$, for any monomial order. In this paper, we will make use of a similar property for submodules of $\mathcal{R}^{m}$; such submodules have Gröbner bases of the form

$$
E=\left[\begin{array}{ccc}
I_{\pi-1} & \lambda_{1} &  \tag{1}\\
& X-\boldsymbol{\alpha} & \\
& \lambda_{2} & I_{m-\pi}
\end{array}\right] \in \mathcal{R}^{(m+r-1) \times m}
$$

for the vector of variables $X=\left[\begin{array}{lll}X_{1} & \cdots & X_{r}\end{array}\right]^{\top}$ and vectors of values $\boldsymbol{\alpha}=\left[\begin{array}{lll}\alpha_{1} & \cdots & \alpha_{r}\end{array}\right]^{\top} \in \mathbb{K}^{r \times 1}, \boldsymbol{\lambda}_{1}=\left[\lambda_{1} \cdots \lambda_{\pi-1}\right]^{\top} \in \mathbb{K}^{(\pi-1) \times 1}$, and $\lambda_{2}=\left[\begin{array}{lll}\lambda_{\pi+1} & \cdots & \lambda_{m}\end{array}\right]^{\top} \in \mathbb{K}^{(m-\pi) \times 1}$. In what follows, such matrices are called elementary Gröbner bases.

Theorem 3.1. Let $\mathcal{M}$ be an $\mathcal{R}$-submodule of $\mathcal{R}^{m}$ such that $\mathcal{R}^{m} / \mathcal{M}$ has dimension 1 as a $\mathbb{K}$-vector space, then for any monomial order $\leqslant$ on $\mathcal{R}^{m}$, the reduced $\leqslant-G r o ̈ b n e r ~ b a s i s ~ E ~ o f ~ \mathcal{M}$ is as in Eq. (1) with $\lambda_{i}=0$ if $\boldsymbol{e}_{i}<\boldsymbol{e}_{\pi}$ for all $i \neq \pi$. Conversely, any matrix $\boldsymbol{E}$ as in $E q$. (1) defines a submodule $\mathcal{M}=\langle E\rangle$ such that $\mathcal{R}^{m} / \mathcal{M}$ has dimension 1 as a $\mathbb{K}$-vector space, and $\boldsymbol{E}$ is a reduced $\leqslant-G r o ̈ b n e r ~ b a s i s ~ f o r ~ a n y ~ m o n o m i a l ~$ order $\leqslant$ such that $\lambda_{i}=0$ if $\boldsymbol{e}_{i}<\boldsymbol{e}_{\pi}$ for all $i \neq \pi$.

Proof. By [11, Thm. 15.3], a basis of $\mathcal{R}^{m} / \mathcal{M}$ as a $\mathbb{K}$-vector space is given by the monomials not in $\operatorname{lm}_{\S}(\mathcal{M})$; since the dimension of $\mathcal{R}^{m} / \mathcal{M}$ as a $\mathbb{K}$-vector space is 1 , there exists a unique monomial which is not in $\operatorname{lm}_{\S}(\mathcal{M})$. Thus there is a unique $\pi \in\{1, \ldots, m\}$ such that

$$
\begin{equation*}
\operatorname{lm}_{\S}(\boldsymbol{E})=\left(\boldsymbol{e}_{1}, \ldots, \boldsymbol{e}_{\pi-1}, X_{1} \boldsymbol{e}_{\pi}, \ldots, X_{r} \boldsymbol{e}_{\pi}, \boldsymbol{e}_{\pi+1}, \ldots, \boldsymbol{e}_{m}\right) \tag{2}
\end{equation*}
$$

By definition of reduced Gröbner bases, the $j$ th polynomial in $E$ is the sum of the $j$ th element of $\operatorname{lm}_{\S}(\boldsymbol{E})$ and a constant multiple of $\boldsymbol{e}_{\pi}$; hence $E$ has the form in Eq. (1). In addition, for $i \neq \pi$, the equality $\operatorname{lm}_{\S}\left(\boldsymbol{e}_{i}+\lambda_{i} \boldsymbol{e}_{\pi}\right)=\boldsymbol{e}_{i}$ implies that $\lambda_{i}=0$ whenever $\boldsymbol{e}_{i}<\boldsymbol{e}_{\pi}$.

For the converse, let $\leqslant$ be such that $\lambda_{i}=0$ if $\boldsymbol{e}_{i}<\boldsymbol{e}_{\pi}$ for all $i \neq \pi$ (such an order exists since there are orders for which $\boldsymbol{e}_{\pi}$ is the smallest coordinate vector). Then $\operatorname{lm}_{\S}(\boldsymbol{E})$ is as in Eq. (2); in particular, the monomials in $\left\langle\operatorname{lm}_{\S}(E)\right\rangle$ are precisely $\operatorname{Mon}\left(\mathcal{R}^{m}\right) \backslash$ $\left\{\boldsymbol{e}_{\pi}\right\}$. It follows that either $\boldsymbol{e}_{\pi} \in \operatorname{lm}_{\S}(\mathcal{M})$ and $\left\langle\operatorname{lm}_{\S}(\mathcal{M})\right\rangle=\mathcal{R}^{m}$, or $\boldsymbol{e}_{\pi} \notin \ln _{\S}(\mathcal{M})$ and $\left\langle\operatorname{lm}_{\S}(\mathcal{M})\right\rangle=\left\langle\operatorname{lm}_{\S}(E)\right\rangle$. In the second case $E$ is a reduced $\leqslant$-Gröbner-basis and $\mathcal{R}^{m} / \mathcal{M}$ has dimension 1 by [11, Thm. 15.3]. To conclude the proof, we show that $\boldsymbol{e}_{\pi} \in \operatorname{lm}_{\S}(\mathcal{M})$ cannot occur; by contradiction, suppose there exists $\boldsymbol{q} \in \mathcal{M}$ such that $\operatorname{lm}_{\S}(\boldsymbol{q})=\boldsymbol{e}_{\pi}$. Since the rows of $\boldsymbol{E}$ generate $\mathcal{M}$, we can write

$$
\begin{aligned}
\boldsymbol{q} & =\left(q_{1}, \ldots, q_{\pi-1}, p_{1}, \ldots, p_{r}, q_{\pi+1}, \ldots, q_{m}\right) \boldsymbol{E} \\
& =\left(q_{1}, \ldots, q_{\pi-1}, \sum_{i \neq \pi} q_{i} \lambda_{i}+\sum_{j=1}^{r}\left(X_{j}-\alpha_{j}\right) p_{j}, q_{\pi+1}, \ldots, q_{m}\right)
\end{aligned}
$$

For $i \neq \pi$ such that $\boldsymbol{e}_{\pi}<\boldsymbol{e}_{i}$, any nonzero term of $q_{i} \boldsymbol{e}_{i}$ would appear in $\boldsymbol{q}$ and be greater than $\boldsymbol{e}_{\pi}$, hence $q_{i}=0$. Moreover, for $i \neq \pi$ such that $\boldsymbol{e}_{i}<\boldsymbol{e}_{\pi}$ we have $\lambda_{i}=0$. Thus, considering the $\pi$ th component of $\boldsymbol{q}$ yields the equality

$$
1=\sum_{i \neq \pi} q_{i} \lambda_{i}+\sum_{j=1}^{r}\left(X_{j}-\alpha_{j}\right) p_{j}=\sum_{j=1}^{r}\left(X_{j}-\alpha_{j}\right) p_{j}
$$

which is a contradiction since $1 \notin\left\langle X_{1}-\alpha_{1}, \ldots, X_{r}-\alpha_{r}\right\rangle$.
Remark that in the module case $(m \geq 2)$ the reduced $\leqslant$-Gröbner basis depends on the order $\leqslant$, more precisely on how the $\boldsymbol{e}_{i}$ 's are ordered by $\leqslant$. For instance, the matrix in Example 2.3 is a reduced $\leqslant$-Gröbner basis for every order such that $\boldsymbol{e}_{1} \leqslant \boldsymbol{e}_{2}$, whereas for orders such that $\boldsymbol{e}_{2} \leqslant \boldsymbol{e}_{1}$ the reduced $\leqslant$-Gröbner basis of the same module is

$$
E=\left[\begin{array}{cc}
1 & 1 \\
0 & X \\
0 & Y
\end{array}\right] \in \mathbb{K}[X, Y]^{3 \times 2}
$$

### 3.2 Multiplication by elementary Gröbner basis

Let $\leqslant$ be a monomial order on $\mathcal{R}^{m}$ and let $\boldsymbol{P}=\left(\boldsymbol{p}_{1}, \ldots, \boldsymbol{p}_{k}\right) \in \mathcal{R}^{k \times m}$ be a $\leqslant$-Gröbner basis. In this section, we show conditions on an elementary Gröbner basis $E$ to ensure that $E P$ is a $\leqslant$-Gröbner basis.

We write $L=\left(\mu_{1}, \ldots, \mu_{k}\right)$ for $\operatorname{lm}_{\S}(P)$, that is, $\mu_{i}=\operatorname{lm}_{\S}\left(\boldsymbol{p}_{i}\right)$ for $1 \leq i \leq k$. Let $\leqslant_{L}$ be a Schreyer order for $\leqslant$ and $P$, and consider a reduced $\leqslant_{L}$-Gröbner basis $E \in \mathcal{R}^{(k+r-1) \times k}$ which has the form in Eq. (1); thus

$$
\begin{aligned}
\boldsymbol{E} \boldsymbol{P}= & \left(\boldsymbol{p}_{1}+\lambda_{1} \boldsymbol{p}_{\pi}, \ldots, \boldsymbol{p}_{\pi-1}+\lambda_{\pi-1} \boldsymbol{p}_{\pi}\right. \\
& \left(X_{1}-\alpha_{1}\right) \boldsymbol{p}_{\pi}, \ldots,\left(X_{r}-\alpha_{r}\right) \boldsymbol{p}_{\pi} \\
& \left.\lambda_{\pi+1} \boldsymbol{p}_{\pi}+\boldsymbol{p}_{\pi+1}, \ldots, \lambda_{k} \boldsymbol{p}_{\pi}+\boldsymbol{p}_{k}\right)
\end{aligned}
$$

which is in $\mathcal{R}^{(k+r-1) \times m}$. We will show that, under suitable assumptions, $E P$ is a $\leqslant$-Gröbner basis; the next lemmas use the above notation. We start by describing the leading terms of $\boldsymbol{E P}$.

Lemma 3.2. If $\boldsymbol{\mu}_{\boldsymbol{i}} \neq \boldsymbol{\mu}_{\pi}$ for all $i \neq \pi$, then

$$
\begin{aligned}
\operatorname{lm}_{\S}(E P) & =\operatorname{lm}_{\leqslant L}(E) L \\
& =\left(\mu_{1}, \ldots, \mu_{\pi-1}, X_{1} \mu_{\pi}, \ldots, X_{r} \mu_{\pi}, \mu_{\pi+1}, \ldots, \mu_{k}\right) .
\end{aligned}
$$

Proof. First, $\operatorname{lm}_{\S}\left(\left(X_{j}-\alpha_{j}\right) \boldsymbol{p}_{\pi}\right)=X_{j} \boldsymbol{\mu}_{\pi}$ for $1 \leq j \leq r$. Next we claim that $\operatorname{lm}_{\S}\left(\boldsymbol{p}_{i}+\lambda_{i} \boldsymbol{p}_{\pi}\right)=\boldsymbol{\mu}_{i}$ for all $i \neq \pi$. If $\lambda_{i}=0$, the identity is obvious. If $\lambda_{i} \neq 0$, then $\boldsymbol{e}_{\pi} \leqslant_{L} \boldsymbol{e}_{i}$ (see Section 3.1), and from
the definition of a Schreyer order and the assumption $\boldsymbol{\mu}_{\pi} \neq \boldsymbol{\mu}_{i}$, we deduce $\boldsymbol{\mu}_{\pi}<\boldsymbol{\mu}_{i}$ and hence $\operatorname{lm}_{\S}\left(\boldsymbol{p}_{i}+\lambda_{i} \boldsymbol{p}_{\pi}\right)=\boldsymbol{\mu}_{i}$.

Next, we characterize the fact that $E P$ generates a submodule which differs from the one generated by $P$.

Lemma 3.3. If $\boldsymbol{\mu}_{i} \neq \boldsymbol{\mu}_{\pi}$ for all $i \neq \pi$, then

$$
\langle E P\rangle \neq\langle P\rangle \Leftrightarrow p_{\pi} \notin\langle E P\rangle \Leftrightarrow \mu_{\pi} \notin\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle
$$

Proof. First, remark that $\langle E P\rangle=\langle P\rangle \Rightarrow \boldsymbol{p}_{\pi} \in\langle E P\rangle \Rightarrow \mu_{\pi} \in$ $\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle$ is obvious; thus, to conclude the proof it remains to show that $\langle E P\rangle=\langle P\rangle \Leftarrow \mu_{\pi} \in\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle$. Suppose that $\mu_{\pi} \in\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle$. Then, since $\mu_{i} \in\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle$ for all $i \neq \pi$ by Lemma 3.2, we have $\operatorname{lm}_{\S}(\boldsymbol{P}) \subset\left\langle\operatorname{lm}_{\S}(\langle\boldsymbol{E} \boldsymbol{P}\rangle)\right\rangle$, hence $\left\langle\operatorname{lm}_{\S}(\boldsymbol{P})\right\rangle \subset$ $\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle$. Furthermore, recall that $\left\langle\operatorname{lm}_{\preccurlyeq}(P)\right\rangle=\left\langle\operatorname{lm}_{\preccurlyeq}(\langle P\rangle)\right\rangle$ since $P$ is a $\leqslant$-Gröbner basis, and that $\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle \subset\left\langle\operatorname{lm}_{\S}(\langle P\rangle)\right\rangle$ since $\langle E P\rangle \subset\langle P\rangle$ : we obtain $\left\langle\operatorname{lm}_{\S}(\langle P\rangle)\right\rangle=\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle$. Then, [11, Lemma 15.5] shows that $\langle\boldsymbol{E P}\rangle=\langle\boldsymbol{P}\rangle$.

For example, if $\boldsymbol{P}$ is a minimal $\leqslant$-Gröbner basis, then the assumption in the previous lemma is satisfied. Example 3.6 below exhibits a case where $\boldsymbol{P}$ is a minimal $\leqslant$-Gröbner basis and $\boldsymbol{p}_{\pi}$ does belong to $\langle E P\rangle$. In that case, $\langle E P\rangle=\langle P\rangle$ and $E P$ is not a Gröbner basis since $\boldsymbol{\mu}_{\pi}$ is in $\left\langle\operatorname{lm}_{\preccurlyeq}(\langle E P\rangle)\right\rangle$ but not in $\left\langle\operatorname{lm}_{\preccurlyeq}(E P)\right\rangle$.

Lemma 3.4. If $\boldsymbol{\mu}_{i} \neq \boldsymbol{\mu}_{\pi}$ for all $i \neq \pi$ and $\langle\boldsymbol{E} \boldsymbol{P}\rangle \neq\langle\boldsymbol{P}\rangle$, then $\boldsymbol{E P}$ is $a \leqslant-$ Gröbner basis.

Proof. Suppose by contradiction that $E P$ is not a $\leqslant$-Gröbner basis. Then there exists a nonzero $h \in\langle E P\rangle$ such that $\operatorname{lm}_{\S}(\boldsymbol{h}) \notin$ $\left\langle\operatorname{lm}_{\S}(\boldsymbol{E P})\right\rangle$, that is, by Lemma 3.2, $\operatorname{lm}_{\S}(\boldsymbol{h})$ is not divisible by any of the elements $\boldsymbol{\mu}_{i}$ for $i \neq \pi$ and $X_{j} \boldsymbol{\mu}_{\pi}$ for $1 \leq j \leq r$. On the other hand, $\operatorname{lm}_{\S}(\boldsymbol{h})$ is in $\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle$ and therefore in $\left\langle\operatorname{lm}_{\S}(\boldsymbol{P})\right\rangle$, hence $\operatorname{lm}_{\nwarrow}(\boldsymbol{h})$ is divisible by at least one $\mu_{i}, 1 \leq i \leq k$. These divisibility constraints lead to $\operatorname{lm}_{\S}(\boldsymbol{h})=\boldsymbol{\mu}_{\pi}$, which implies $\boldsymbol{\mu}_{\pi} \in\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle$. From Lemma 3.3 one deduces $\langle\boldsymbol{E P}\rangle=\langle\boldsymbol{P}\rangle$, which is absurd.

Corollary 3.5. Assume that $\langle\boldsymbol{E} \boldsymbol{P}\rangle \neq\langle\boldsymbol{P}\rangle$ and that $\boldsymbol{P}$ is a minimal $\leqslant-$ Gröbner basis. Let $j_{1}<\cdots<j_{\ell}$ be the indices $j \in\{1, \ldots, r\}$ such that $X_{j} \mu_{\pi} \notin\left\langle\mu_{i}, i \neq \pi\right\rangle$. Then, the submatrix

$$
Q=\left[\begin{array}{ccc}
\boldsymbol{I}_{\pi-1} & \lambda_{1} &  \tag{3}\\
& X_{j_{1}}-\alpha_{j_{1}} & \\
& \vdots & \\
& X_{j_{\ell}}-\alpha_{j_{\ell}} & \\
& \lambda_{2} & I_{m-\pi}
\end{array}\right] \in \mathcal{R}^{(k+\ell-1) \times k}
$$

of $E$ is such that $Q P$ is a minimal $\leqslant-G r o ̈ b n e r ~ b a s i s ~ o f ~\langle E P\rangle$.
Proof. Since $\boldsymbol{P}$ is minimal, $\boldsymbol{\mu}_{i} \neq \boldsymbol{\mu}_{\boldsymbol{\pi}}$ for all $i \neq \pi$. Then, Lemma 3.4 ensures that $\boldsymbol{E P}$ is a $\leqslant$-Gröbner basis and Lemma 3.2 gives

$$
\operatorname{lm}_{\preccurlyeq}(Q P)=\left(\boldsymbol{\mu}_{1}, \ldots, \boldsymbol{\mu}_{\pi-1}, X_{j_{1}} \boldsymbol{\mu}_{\pi}, \ldots, X_{j_{\ell}} \boldsymbol{\mu}_{\pi}, \boldsymbol{\mu}_{\pi+1}, \ldots, \boldsymbol{\mu}_{k}\right)
$$

By construction of $j_{1}, \ldots, j_{\ell}$, one has $\left\langle\operatorname{lm}_{\preccurlyeq}(Q P)\right\rangle=\left\langle\operatorname{lm}_{\lessgtr}(E P)\right\rangle$, which implies

$$
\begin{aligned}
\left\langle\operatorname{lm}_{\S}(\langle E P\rangle)\right\rangle=\left\langle\operatorname{lm}_{\S}(E P)\right\rangle & =\left\langle\operatorname{lm}_{\preccurlyeq}(Q P)\right\rangle \\
& \subset\left\langle\operatorname{lm}_{\preccurlyeq}(\langle Q P\rangle)\right\rangle \subset\left\langle\operatorname{lm}_{\preccurlyeq}(\langle E P\rangle)\right\rangle .
\end{aligned}
$$

Hence $\left\langle\operatorname{lm}_{\S}(Q P)\right\rangle=\left\langle\operatorname{lm}_{\S}(\langle Q P\rangle)\right\rangle$, and $Q P$ is a minimal $\preccurlyeq$-Gröbner basis. Moreover, by [11, Lem. 15.5], $\langle Q P\rangle \subset\langle E P\rangle$ and $\left\langle\operatorname{lm}_{\S}(\langle Q P\rangle)\right\rangle=$ $\left\langle\operatorname{lm}_{\preccurlyeq}(\langle E P\rangle)\right\rangle$ imply that $\langle Q P\rangle=\langle E P\rangle$.

Example 3.6. Consider the case $\mathcal{R}=\mathbb{K}[X, Y]$ and $m=1$. Let $\boldsymbol{P}=\left[\begin{array}{c}X \\ Y+1\end{array}\right] \in \mathcal{R}^{2 \times 1}$, which is the reduced $\leqslant_{1}$-Gröbner basis of $\langle X, Y+1\rangle$ for any monomial order $\leqslant_{1}$ on $\operatorname{Mon}(\mathcal{R})$. Let also $E \in \mathcal{R}^{3 \times 2}$ whose rows are ( $X \boldsymbol{e}_{1}, Y \boldsymbol{e}_{1}, \boldsymbol{e}_{2}$ ); according to Theorem 3.1, $\boldsymbol{E}$ is a reduced $\leqslant_{2}$-Gröbner basis for any monomial order $\leqslant_{2}$ on $\operatorname{Mon}\left(\mathcal{R}^{2}\right)$. Now, the product $E P \in \mathcal{R}^{3 \times 1}$ has entries $X^{2}, X Y$, and $Y+1$. Thus, $\left\langle\operatorname{lm}_{\nwarrow_{3}}(E P)\right\rangle=\left\langle X^{2}, X Y, Y\right\rangle=\left\langle X^{2}, Y\right\rangle$ for any monomial order $\leqslant_{3}$ on $\operatorname{Mon}(\mathcal{R})$. On the other hand, $\langle E P\rangle$ contains $X=X(Y+1)-X Y$, hence $\left\langle\operatorname{lm}_{\lessgtr_{3}}(E P)\right\rangle \neq\left\langle\operatorname{lm}_{\lessgtr_{3}}(\langle E P\rangle)\right\rangle$, which means that $E P$ is not a $\leqslant_{3}$-Gröbner basis.

### 3.3 Algorithm

We now describe Algorithm Syzygy_BaseCase, which will serve as the base case of the divide and conquer scheme.

```
Algorithm 1 Syzygy_BASECASE \((\varphi, G, \preccurlyeq, L)\)
Input:
    - a linear functional \(\varphi: \mathcal{R}^{n} \rightarrow \mathbb{K}\),
    - a matrix \(G\) in \(\mathcal{R}^{k \times n}\) with rows \(\boldsymbol{g}_{1}, \ldots, \boldsymbol{g}_{k} \in \mathcal{R}^{n}\),
    - a monomial order \(\leqslant\) on \(\mathcal{R}^{m}\),
    - a list \(K=\left(\boldsymbol{\mu}_{1}, \ldots, \boldsymbol{\mu}_{k}\right)\) of monomials in \(\operatorname{Mon}\left(\mathcal{R}^{m}\right)\).
Output:
    - a matrix \(Q\) in \(\mathcal{R}^{(k+\ell-1) \times k}\) for some \(\ell \in\{0, \ldots, r\}\),
    - a list \(L\) of \(k+\ell-1\) monomials in \(\operatorname{Mon}\left(\mathcal{R}^{k}\right)\).
    \(\left(v_{1}, \ldots, v_{k}\right) \leftarrow\left(\varphi\left(\boldsymbol{g}_{1}\right), \ldots, \varphi\left(\boldsymbol{g}_{k}\right)\right) \in \mathbb{K}^{k}\)
    if \(\left(v_{1}, \ldots, v_{k}\right)=(0, \ldots, 0)\) then return \(\left(\boldsymbol{I}_{k}, \boldsymbol{K}\right)\)
    \(\leqslant_{K} \leftarrow \operatorname{SchreyerOrder}(\leqslant, K)\)
    \(\pi \leftarrow \arg \min _{\leqslant_{K}}\left\{\boldsymbol{e}_{i} \mid 1 \leq i \leq k, v_{i} \neq 0\right\} \quad \triangleright\) the index \(i\) such that
    \(v_{i} \neq 0\) which minimizes \(\boldsymbol{e}_{i}\) with respect to \(\leqslant_{K}\)
    \(\left\{j_{1}<\cdots<j_{\ell}\right\} \leftarrow\left\{j \in\{1, \ldots, r\} \mid X_{j} \boldsymbol{\mu}_{\pi} \notin\left\langle\boldsymbol{\mu}_{i}, i \neq \pi\right\rangle\right\}\)
    \(\alpha_{j_{s}} \leftarrow \varphi\left(X_{j_{s}} \boldsymbol{g}_{\pi}\right) / v_{\pi}\) for \(1 \leq s \leq \ell\)
    \(\lambda_{i} \leftarrow-v_{i} / v_{\pi}\) for \(1 \leq i<\pi\) and \(\pi<i \leq k\)
    \(Q \leftarrow\) matrix in \(\mathcal{R}^{(k+\ell-1) \times k}\) as in Eq. (3)
    \(\boldsymbol{L} \leftarrow\left(\boldsymbol{\mu}_{1}, \ldots, \boldsymbol{\mu}_{\pi-1}, X_{j_{1}} \boldsymbol{\mu}_{\pi}, \ldots, X_{j_{\ell}} \boldsymbol{\mu}_{\pi}, \boldsymbol{\mu}_{\pi+1}, \ldots, \boldsymbol{\mu}_{k}\right)\)
    return \((Q, L)\)
```

Theorem 3.7. Let $\mathcal{N} \subset \mathcal{R}^{n}$ be an $\mathcal{R}$-submodule, let $\boldsymbol{F} \in \mathcal{R}^{m \times n}$, and let $\boldsymbol{P} \in \mathcal{R}^{k \times m}$ be a minimal $\preccurlyeq-G r o ̈ b n e r ~ b a s i s ~ o f \operatorname{Syz}_{\mathcal{N}}(\boldsymbol{F})$ for some monomial order $\leqslant$ on $\mathcal{R}^{m}$. Assume that the input of Algorithm 1 is such that $\operatorname{ker}(\varphi) \cap \mathcal{N}$ is an $\mathcal{R}$-module, $G=P F$, and $\operatorname{lm}_{\S}(P)=$ $\left(\boldsymbol{\mu}_{1}, \ldots, \boldsymbol{\mu}_{k}\right)$. Then Algorithm 1 returns $(Q, L)$ such that $Q P$ is a minimal $\preccurlyeq-G r o ̈ b n e r ~ b a s i s ~ o f ~ S y z ~\left(~ k e r ~(\varphi) \cap \mathcal{N}, ~(F)\right.$ and $L=\operatorname{lm}_{\preccurlyeq}(Q P)$.

Proof. If $\left(\varphi\left(\boldsymbol{g}_{1}\right), \ldots, \varphi\left(\boldsymbol{g}_{k}\right)\right)=(0, \ldots, 0)$, then Algorithm 1 stops at Line 2 and returns $Q=I_{k}$ and $\boldsymbol{K}$. Thus $Q P=P$, hence by assumption $L=K=\operatorname{lm}_{\S}(P)=\operatorname{lm}_{\S}(Q P)$, and $Q P$ is a minimal $\leqslant$-Gröbner basis of $\operatorname{Syz}_{\mathcal{N}}(F)$; besides, the identity $\operatorname{Syz}_{\mathcal{N}}(F)=\operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(F)$ is easily deduced from $\left(\varphi\left(\boldsymbol{g}_{1}\right), \ldots, \varphi\left(\boldsymbol{g}_{k}\right)\right)=(0, \ldots, 0)$.

In the rest of the proof, assume $\left(\varphi\left(\boldsymbol{g}_{1}\right), \ldots, \varphi\left(\boldsymbol{g}_{k}\right)\right) \neq(0, \ldots, 0)$. Define $E \in \mathcal{R}^{(k+r-1) \times k}$ as in Eq. (1) with $\pi$ and $\lambda_{i}$ as in Algorithm 1 and $\alpha_{j}=\varphi\left(X_{j} \boldsymbol{g}_{\pi}\right) / v_{\pi}$ for $1 \leq j \leq r$; in particular, $Q$ computed at Line 8 is formed by a subset of the rows of $E$.

First, $E$ is a $\leqslant_{K}$-Gröbner basis according to Theorem 3.1, since by definition of $\pi$ and $\lambda_{i}$ one gets the implications $\boldsymbol{e}_{i} \leqslant_{K} \boldsymbol{e}_{\pi} \Rightarrow$ $v_{i}=0 \Rightarrow \lambda_{i}=0$, for $i \neq \pi$.

Next, we claim that $\langle\boldsymbol{E}\rangle=\operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(\boldsymbol{G})$. Indeed, the rows of $P F$ are in $\mathcal{N}$, and thus so are those of $E G=E P F$. Moreover, by choice of $\pi$ and $\lambda_{i}$ the rows of $E G$ are in $\operatorname{ker}(\varphi)$, since for $i \neq \pi$ one has $\varphi\left(\left(\boldsymbol{p}_{i}+\lambda_{i} \boldsymbol{p}_{\pi}\right) \boldsymbol{F}\right)=\varphi\left(\boldsymbol{g}_{i}+\lambda_{i} \boldsymbol{g}_{\pi}\right)=v_{i}+\lambda_{i} v_{\pi}=0$ and for $1 \leq j \leq r$ one has $\varphi\left(\left(X_{j}-\alpha_{j}\right) \boldsymbol{p}_{\pi} \boldsymbol{F}\right)=\varphi\left(\left(X_{j}-\alpha_{j}\right) \boldsymbol{g}_{\pi}\right)=$ $\varphi\left(X_{j} \boldsymbol{p}_{\pi}\right)-\alpha_{j} v_{\pi}=0$. Therefore the rows of $\boldsymbol{E} G$ are in $\operatorname{ker}(\varphi) \cap \mathcal{N}$, that is, $\langle E\rangle \subset \operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(\boldsymbol{G})$. To prove the reverse inclusion, recall from Theorem 3.1 that $\langle E\rangle$ has codimension 1 in $\mathcal{R}^{k}$ and hence $\operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(\boldsymbol{G})$ is either $\langle\boldsymbol{E}\rangle$ or $\mathcal{R}^{k}$. Since

$$
0 \neq v_{\pi}=\varphi\left(\boldsymbol{g}_{\pi}\right)=\varphi\left(\boldsymbol{p}_{\pi} \boldsymbol{F}\right)=\varphi\left(\boldsymbol{e}_{\pi} \boldsymbol{P F}\right)=\varphi\left(\boldsymbol{e}_{\pi} \boldsymbol{G}\right)
$$

one has that $\boldsymbol{e}_{\pi} \notin \operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(G)$, hence $\operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(G)=\langle E\rangle$.
It follows that $\langle E P\rangle=\operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(F)$. Indeed, the rows of $E P F$ are in $\operatorname{ker}(\varphi) \cap \mathcal{N}$ as noted above, and thus $\langle E P\rangle \subset \operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(F)$. Now let $\boldsymbol{p} \in \operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(\boldsymbol{F})$; thus in particular $\boldsymbol{p} \in \operatorname{Syz}_{\mathcal{N}}(F)$, and $\boldsymbol{p}=\boldsymbol{q} \boldsymbol{P}$ for some $\boldsymbol{q} \in \mathcal{R}^{k}$. Then $\boldsymbol{p} \boldsymbol{F}=\boldsymbol{q} \boldsymbol{P F}=\boldsymbol{q} G \in \operatorname{ker}(\varphi) \cap \mathcal{N}$, hence $\boldsymbol{q} \in \operatorname{Syz}_{\mathrm{ker}(\varphi) \cap \mathcal{N}}(\boldsymbol{G})=\langle\boldsymbol{E}\rangle$, and therefore $\boldsymbol{p} \in\langle\boldsymbol{E} \boldsymbol{P}\rangle$.

Now, $\varphi\left(\boldsymbol{p}_{\pi} \boldsymbol{F}\right) \neq 0$ implies $\boldsymbol{p}_{\pi} \notin \operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(\boldsymbol{F})=\langle\boldsymbol{E} \boldsymbol{P}\rangle$. Thus Lemma 3.3 ensures $\langle\boldsymbol{E P}\rangle \neq\langle\boldsymbol{P}\rangle$, and finally Corollary 3.5 states that $Q P$ is a minimal $\leqslant-\operatorname{Gröbner}$ basis of $\langle E P\rangle=\operatorname{Syz}_{\operatorname{ker}(\varphi) \cap \mathcal{N}}(F)$. Besides Lemma 3.2 yields $\operatorname{lm}_{\S}(Q P)=\operatorname{lm}_{\lessgtr_{K}}(Q) K=L$.

## 4 DIVIDE AND CONQUER ALGORITHM

Repeating the basic procedure described in Section 3.3 iteratively, we obtain an algorithm for syzygy basis computation when $\mathcal{N}$ is an intersection of kernels of linear functionals with a specific property (see Eq. (4)). This algorithm is similar to [20, Algo. 2] and [25, Algo. 3.2], apart from differences in the input description. Here, the input consists of linear functionals $\varphi_{1}, \ldots, \varphi_{D}: \mathcal{R}^{n} \rightarrow \mathbb{K}$, with the assumption that

$$
\begin{equation*}
\mathcal{N}_{i}=\cap_{1 \leq j \leq i} \operatorname{ker}\left(\varphi_{j}\right) \text { is an } \mathcal{R} \text {-module for } 1 \leq i \leq D . \tag{4}
\end{equation*}
$$

Then we consider the $\mathcal{R}$-module $\mathcal{N}=\mathcal{N}_{D}=\cap_{1 \leq j \leq D} \operatorname{ker}\left(\varphi_{j}\right)$, which is such that $\mathcal{R}^{n} / \mathcal{N}$ has dimension at most $D$ as a $\mathbb{K}$-vector space. For $F$ in $\mathcal{R}^{m \times n}$, the following algorithm computes a minimal $\leqslant-$ Gröbner basis of the syzygy module $\mathrm{Syz}_{\mathcal{N}}(F)$. Note that we do not specify the representation of $F$ since it may depend on the specific functionals $\varphi_{i}$; typically, one considers $F$ to be known modulo $\mathcal{N}$, via the images of its rows by the functionals $\varphi_{i}$.

```
Algorithm 2 Syzygy_ITER \(\left(\varphi_{1}, \ldots, \varphi_{D}, \boldsymbol{F}, \preccurlyeq\right)\)
Input:
    - linear functionals \(\varphi_{1}, \ldots, \varphi_{D}: \mathcal{R}^{n} \rightarrow \mathbb{K}\) such that Eq. (4),
    - a matrix \(\boldsymbol{F}\) in \(\mathcal{R}^{m \times n}\),
    - a monomial order \(\leqslant\) on \(\mathcal{R}^{m}\).
Output:
```



```
    \(P \leftarrow I_{m} \in \mathcal{R}^{m \times m} ; G \leftarrow F ; L \leftarrow\left(\boldsymbol{e}_{1}, \ldots, \boldsymbol{e}_{m}\right)=\operatorname{lm}_{\S}(P)\)
    for \(i=1, \ldots, D\) do
        \((Q, L) \leftarrow \operatorname{Syzygy}\) BaseCase \(\left(\varphi_{i}, \boldsymbol{G}, \leqslant, \boldsymbol{L}\right)\)
        \(P \leftarrow Q P ; G \leftarrow Q G\)
    return \(P\)
```

Corollary 4.1. At the end of the ith iteration of Algorithm 2, $\mathbf{P}$ is a minimal $\preccurlyeq-G r o ̈ b n e r ~ b a s i s ~ o f ~ S y z ~ \mathcal{N}_{i}(F)$, and one has $G=P F$ as well as $L=\operatorname{lm}_{\preccurlyeq(P)}$. In particular, Algorithm 2 is correct.

Proof. Note that at Line 1 of Algorithm 2, $P=I_{m}$ is the reduced $\preccurlyeq$-Gröbner basis of $\mathcal{R}^{m}=\operatorname{Syz}_{\mathcal{N}_{0}}(\boldsymbol{F})$ with $\mathcal{N}_{0}=\mathcal{R}^{n}$, and both $G=P F=F$ and $L=\left(\boldsymbol{e}_{1}, \ldots, \boldsymbol{e}_{m}\right)=\operatorname{lm}_{\preccurlyeq}(\boldsymbol{P})$ hold. We conclude that if $D=0$, Algorithm 2 is correct.

The rest of the proof is by induction on $D$. We claim that the properties in the statement are preserved across the $D$ iterations. Precisely, we assume that at the beginning of the $i$ th iteration, $P$ is a minimal $\preccurlyeq$-Gröbner basis of $\operatorname{Syz}_{\mathcal{N}_{i}}(F), G=P F$, and $L=\operatorname{lm}_{\preccurlyeq}(P)$.

Since $\mathcal{N}_{i+1}=\operatorname{ker}\left(\varphi_{i+1}\right) \cap \mathcal{N}_{i}$ is an $\mathcal{R}$-module, applying Theorem 3.7 shows that $(Q, L)$ computed during the iteration are such that $L=\operatorname{lm}_{\preccurlyeq}(Q P)$ and that $Q P$ is a minimal $\preccurlyeq-G r o ̈ b n e r ~ b a s i s ~ o f ~$ $\mathrm{Syz}_{\mathcal{N}_{i+1}}(F)$.

This allows us to deduce bounds on the size of a minimal $\leqslant-$ Gröbner basis of $\mathrm{Syz}_{\mathcal{N}}(\boldsymbol{F})$.

Lemma 4.2. Let $\boldsymbol{P} \in \mathcal{R}^{k \times m}$ be the output of Algorithm 2. Then, $m \leq k \leq m+(r-1) D$, and thus the same holds for any minimal $\leqslant-G r o ̈ b n e r ~ b a s i s ~ o f ~ S y z ~(\mathcal{N} ~(F) . ~ F u r t h e r m o r e, ~ a t ~ t h e ~ e n d ~ o f ~ t h e ~ i t e r a t i o n ~$ $i$ of Algorithm 2, the basis $Q$ has at most $k+D-i$ elements.

Proof. Remark that all minimal $\preccurlyeq-G r o ̈ b n e r ~ b a s e s ~ o f ~ t h e ~ s a m e ~$ module have the same number of rows. Before the first iteration, the basis is $I_{m}$ which has $m$ rows, and each iteration of the for loop adds $\ell-1$ rows to the basis for some $\ell$ in $\{0, \ldots, r\}$. Therefore $k \leq m+(r-1) D$, and the last claim follows from $\ell-1 \geq-1$. The lower bound $m \leq k$ comes from the fact that $\mathcal{R}^{m} / \mathrm{Syz}_{\mathcal{N}}(F)$ has finite dimension as a $\mathbb{K}$-vector space.

This iterative algorithm can be turned into a divide and conquer one (Algorithm 3), by reorganizing how the products are performed. It computes a minimal $\leqslant-$ Gröbner basis of $\operatorname{Syz}_{\mathcal{N}}(\boldsymbol{F})$, if one takes as input $G=F$ and $K=\left(\boldsymbol{e}_{1}, \ldots, \boldsymbol{e}_{m}\right)$.

```
Algorithm 3 SYZYGY_DAC \(\left(\varphi_{1}, \ldots, \varphi_{D}, \boldsymbol{G}, \preccurlyeq, \boldsymbol{K}\right)\)
Input:
    - linear functionals \(\varphi_{1}, \ldots, \varphi_{D}: \mathcal{R}^{n} \rightarrow \mathbb{K}\),
    - a matrix \(G\) in \(\mathcal{R}^{k \times n}\),
    - a monomial order \(\leqslant\) on \(\mathcal{R}^{m}\),
    - a list \(K=\left(\boldsymbol{\mu}_{1}, \ldots, \boldsymbol{\mu}_{k}\right)\) of monomials in \(\operatorname{Mon}\left(\mathcal{R}^{m}\right)\).
Output:
    - a matrix \(Q\) in \(\mathcal{R}^{\ell \times m}\) for some \(\ell \geq 0\),
    - a list \(L\) of \(\ell\) monomials in \(\operatorname{Mon}\left(\mathcal{R}^{m}\right)\).
    if \(D=1\) then return \(\operatorname{Syzygy} \operatorname{BASECASE}\left(\varphi_{i}, \boldsymbol{G}, \preccurlyeq, \boldsymbol{K}\right)\)
    \(\left(Q_{1}, L_{1}\right) \leftarrow\) SYZYGY_DAC \(\left(\varphi_{1}, \ldots, \varphi_{\lfloor D / 2\rfloor}, G, \leqslant, K\right)\)
    \(\left(\boldsymbol{Q}_{2}, \boldsymbol{L}_{2}\right) \leftarrow\) Syzygy_DAC \(\left(\varphi_{\lfloor D / 2\rfloor+1}, \ldots, \varphi_{D}, \boldsymbol{Q}_{1} \boldsymbol{G}, \leqslant, \boldsymbol{L}_{1}\right)\)
    return \(\left(Q_{2} Q_{1}, L_{2}\right)\)
```

Theorem 4.3. Let $\mathcal{N} \subset \mathcal{R}^{n}$ be an $\mathcal{R}$-submodule, let $F \in \mathcal{R}^{m \times n}$, and let $\boldsymbol{P} \in \mathcal{R}^{k \times m}$ be a minimal $\leqslant-G r o ̈ b n e r ~ b a s i s ~ o f S_{S_{\mathcal{N}}}(\boldsymbol{F})$ for some monomial order $\leqslant$ on $\mathcal{R}^{m}$. Assume that the input of Algorithm 3 is such that $G=P F$, and $\operatorname{lm}_{\preccurlyeq}(P)=\left(\boldsymbol{\mu}_{1}, \ldots, \boldsymbol{\mu}_{k}\right)$, and

$$
\begin{equation*}
\mathcal{N}_{i} \cap \mathcal{N} \text { is an } \mathcal{R} \text {-module for } 1 \leq i \leq D \tag{5}
\end{equation*}
$$

where $\mathcal{N}_{i}=\cap_{1 \leq j \leq i} \operatorname{ker}\left(\varphi_{j}\right)$. Then Algorithm 3 outputs $(Q, L)$ such that $Q P$ is a minimal $\preccurlyeq-G r o ̈ b n e r ~ b a s i s ~ o f ~ S y z ~\left(\mathcal{N}_{D} \cap \mathcal{N}(F)\right.$ and $L=$ $\operatorname{lm}_{\preccurlyeq}(Q P)$.

Proof. If $D=1$ the output returned by Algorithm 1 is correct, since by Theorem 3.7, $Q P$ is a minimal $\preccurlyeq$-Gröbner basis of $\operatorname{Syz}_{\operatorname{ker}\left(\varphi_{1}\right) \cap \mathcal{N}}(F)$ and $L=\operatorname{lm}_{\preccurlyeq}(Q P)$. We assume by induction hypothesis that Algorithm 3 returns the output foreseen by Theorem 4.3 when the number of input linear functionals is $<D$, and when the assumptions of the theorem are satisfied.

By such a hypothesis, since $G=P F$ and $K=\operatorname{lm}_{\preccurlyeq}(P)$, one deduces that $\left(Q_{1}, L_{1}\right)$ are such that $Q_{1} P$ is a $\leqslant$-Gröbner basis of $\operatorname{Syz}_{\mathcal{M}}(F)$, with $\mathcal{M}=\mathcal{N}_{\lfloor D / 2\rfloor} \cap \mathcal{N}$, and $L_{1}=\operatorname{lm}_{\preccurlyeq}\left(Q_{1} P\right)$.

Let $\mathcal{K}_{i}=\cap_{\lfloor D / 2\rfloor+1 \leq j \leq i} \operatorname{ker}\left(\varphi_{j}\right)$, for each $i=\lfloor D / 2\rfloor+1, \ldots, D$. By hypothesis $\mathcal{K}_{i} \cap \mathcal{M}=\mathcal{N}_{i} \cap \mathcal{N}$ is a module, for each $i=\lfloor D / 2\rfloor+$ $1, \ldots, D$. Since $Q_{1} G=Q_{1} P F$ and $Q_{1} P$ is a $\leqslant$-Gröbner basis of $\operatorname{Syz}_{\mathcal{M}}(F)$, and $L_{1}=\operatorname{lm}_{\preccurlyeq}\left(Q_{1} P\right)$, we can apply again the induction hypothesis, and conclude that $\left(Q_{2}, L_{2}\right)$ is such that $Q_{2} Q_{1} P$ is a minimal $\leqslant$-Gröbner basis of $\operatorname{Syz}_{\mathcal{K}_{D} \cap \mathcal{M}}(F)=\operatorname{Syz}_{\mathcal{N}_{D} \cap \mathcal{N}}(F)$, and $L_{2}=\operatorname{lm}_{\preccurlyeq}\left(Q_{2} Q_{1} P\right)$. We conclude that the global output $\left(Q_{2} Q_{1}, L_{2}\right)$ satisfies the claimed properties.

## 5 MULTIVARIATE PADÉ APPROXIMATION

The algorithm in the previous section gives a general framework, which can be refined when applied to a particular context. Here, we consider the context of multivariate Padé approximation, where

$$
\begin{equation*}
\mathcal{N}=\left\langle X_{1}^{d_{1}}, \ldots, X_{r}^{d_{r}}\right\rangle \times \cdots \times\left\langle X_{1}^{d_{1}}, \ldots, X_{r}^{d_{r}}\right\rangle \subseteq \mathcal{R}^{n} \tag{6}
\end{equation*}
$$

for some $d_{1}, \ldots, d_{r} \in \mathbb{Z}_{>0}$. We begin with some remarks on the degrees and sizes of Gröbner bases of syzygy modules $\mathrm{Syz}_{\mathcal{N}}(F)$.

To express this context in the framework of Section 4, we take for the $D$ linear functionals $\varphi_{i}$ the dual basis of the canonical monomial basis of $\mathcal{R}^{n} / \mathcal{N}$. Precisely, the linear functionals are $\varphi_{\mu, j}: \mathcal{R}^{n} \rightarrow \mathbb{K}$ for $1 \leq j \leq n$ and all monomials $\mu \in \operatorname{Mon}(\mathcal{R})$ with $\operatorname{deg}_{X_{i}}(\mu)<d_{i}$ for $1 \leq i \leq r$, defined as follows: for $f=\left(f_{1}, \ldots, f_{n}\right) \in \mathcal{R}^{n}, \varphi_{\mu, j}(f)$ is the coefficient of the monomial $\mu$ in $f_{j}$. These linear functionals can be ordered in several ways to ensure that Eq. (4) is satisfied. Here we design our algorithm by ordering the functionals $\varphi_{\mu, j}$ according to the term-over-position lexicographic order on the monomials $\mu \boldsymbol{e}_{j} \in \operatorname{Mon}\left(\mathcal{R}^{n}\right)$.

Example 5.1. Consider the case of $r=2$ variables $X, Y$ with $d_{1}=2, d_{2}=4$, and $n=2$. Then the functionals are

$$
\begin{aligned}
& \varphi_{1,1}, \varphi_{1,2}, \quad \varphi_{Y, 1}, \quad \varphi_{Y, 2}, \quad \varphi_{Y^{2}, 1}, \quad \varphi_{Y^{2}, 2}, \quad \varphi_{Y^{3}, 1}, \quad \varphi_{Y^{3}, 2} \\
& \varphi_{X, 1}, \varphi_{X, 2}, \varphi_{X Y, 1}, \varphi_{X Y, 2}, \varphi_{X Y^{2}, 1}, \varphi_{X Y^{2}, 2}, \varphi_{X Y^{3}, 1}, \varphi_{X Y^{3}, 2}
\end{aligned}
$$

in that specific order.
Lemma 5.2. Let $\mathcal{N}$ be as in Eq. (6), let $\boldsymbol{F} \in \mathcal{R}^{m \times n}$, and let $\leqslant$ be a monomial order on $\mathcal{R}^{m}$. Then, for $1 \leq i \leq r$, each polynomial in the reduced $\leqslant-$ Gröbner basis of $\mathrm{Syz}_{\mathcal{N}}(\boldsymbol{F})$ either has degree in $X_{i}$ less than $d_{i}$ or has the form $X_{i}^{d_{i}} \boldsymbol{e}_{j}$ for some $1 \leq j \leq m$.

Proof. Let $P$ be the reduced $\leqslant$-Gröbner basis of $\operatorname{Syz}_{\mathcal{N}}(F)$ and let $i \in\{1, \ldots, r\}$. Since $\mathcal{R}^{m} / \operatorname{Syz}_{\mathcal{N}}(\boldsymbol{F})$ has finite dimension as a $\mathbb{K}$-vector space, for each $j \in\{1, \ldots, n\}$ there is a polynomial in $P$ whose $\leqslant$-leading monomial has the form $X_{i}^{d} \boldsymbol{e}_{j}$ for some $d \geq 0$. Since
$\boldsymbol{P}$ is reduced, any other $\left(p_{1}, \ldots, p_{m}\right)$ in $\boldsymbol{P}$ whose $\leqslant$-leading monomial has support $j$ is such that $\operatorname{deg}_{X_{i}}\left(p_{j}\right)<d \leq d_{i}$; the last inequality follows from the fact that the monomial $X_{i}^{d_{i}} \boldsymbol{e}_{j}$ is in $\mathrm{Syz}_{\mathcal{N}}(F)$ and thus is a multiple of $X_{i}^{d} \boldsymbol{e}_{j}$. It follows that all polynomials in $\boldsymbol{P}$ whose $\leqslant$-leading monomial is not among $\left\{X_{i}^{d_{i}} \boldsymbol{e}_{j}, 1 \leq j \leq n\right\}$ must have degree in $X_{i}$ less than $d_{i}$. On the other hand, any polynomial in $P$ whose $\leqslant$-leading monomial is $X_{i}^{d_{i}} \boldsymbol{e}_{j}$ for some $j$ must be equal to this monomial, since it belongs to $\mathrm{Syz}_{\mathcal{N}}(\boldsymbol{F})$ and $\boldsymbol{P}$ is reduced.

In the context of Algorithm 3, Lemma 5.2 allows us to truncate the product $Q_{2} Q_{1}$ while preserving a $\leqslant$-Gröbner basis.

Corollary 5.3. Let $\mathcal{N}$ be as in Eq. (6), let $F \in \mathcal{R}^{m \times n}$, let $\leqslant$ be a monomial order on $\mathcal{R}^{m}$, and let $\boldsymbol{P} \in \mathcal{R}^{k \times m}$ be a minimal $\leqslant-$ Gröbner basis of $\mathrm{Syz}_{\mathcal{N}}(\boldsymbol{F})$. If $\boldsymbol{P}$ is modified by truncating each of its polynomials modulo $\left\langle X_{1}^{d_{1}+1}, \ldots, X_{r}^{d_{r}+1}\right\rangle$, then $P$ is still a minimal $\leqslant-$ Gröbner basis of $\mathrm{Syz}_{\mathcal{N}}(F)$.

Proof. On the first hand, this modification of $P$ does not affect the $\leqslant$-leading terms since they all have $X_{i}$-degree less than $d_{i}+1$ according to Lemma 5.2, hence after modification we still have $\left\langle\operatorname{lm}_{\S}(P)\right\rangle=\left\langle\operatorname{lm}_{\preccurlyeq}\left(\operatorname{Syz}_{\mathcal{N}}(F)\right)\right\rangle$. On the other hand, after this modification we also have $\langle P\rangle \subseteq \operatorname{Syz}_{\mathcal{N}}(F)$ since we started from a basis of $\mathrm{Syz}_{\mathcal{N}}(F)$ and added to each of its elements some elements of $\left\langle X_{1}^{d_{1}+1}, \ldots, X_{r}^{d_{r}+1}\right\rangle$, which is contained in $\mathrm{Syz}_{\mathcal{N}}(F)$. Then [11, Lem. 15.5] yields $\langle P\rangle=\mathrm{Syz}_{\mathcal{N}}(F)$, hence the conclusion.

The divide and conquer algorithm can then be refined as follows.

```
Algorithm \(\left.4 \operatorname{PADÉ(~} d_{1}, \ldots, d_{r}, G, \leqslant, K\right)\)
Input:
    - integers \(d_{1}, \ldots, d_{r} \in \mathbb{Z}_{>0}\),
    - a matrix \(G\) in \(\mathcal{R}^{k \times n}\),
    - a monomial order \(\leqslant\) on \(\mathcal{R}^{m}\),
    - a list \(K=\left(\boldsymbol{\mu}_{1}, \ldots, \boldsymbol{\mu}_{k}\right)\) of monomials in \(\operatorname{Mon}\left(\mathcal{R}^{m}\right)\).
Output:
    - a matrix \(Q\) in \(\mathcal{R}^{\ell \times m}\) for some \(\ell \geq 0\),
    - a list \(L\) of \(\ell\) monomials in \(\operatorname{Mon}\left(\mathcal{R}^{m}\right)\).
    if \(d_{1}=\cdots=d_{r}=1\) then
        \(\boldsymbol{Q} \in \mathcal{R}^{k \times k} \leftarrow I_{k} ; \boldsymbol{H} \leftarrow G \bmod X_{1}, \ldots, X_{r} ; \boldsymbol{L} \leftarrow K\)
        for \(i=1, \ldots, n\) do
                \(\varphi \leftarrow\) linear functional \(\mathcal{R}^{n} \rightarrow \mathbb{K}\) defined by \(\varphi(f)=f_{i}(\mathbf{0})\)
                \(\left(\boldsymbol{Q}_{i}, \boldsymbol{L}\right) \leftarrow \operatorname{SyzYGY} \operatorname{BASECASE}(\varphi, \boldsymbol{H}, \leqslant, \boldsymbol{L})\)
                \(Q \leftarrow Q_{i} Q \bmod X_{1}^{2}, \ldots, X_{r}^{2}\)
                \(H \leftarrow Q_{i} H \bmod X_{1}, \ldots, X_{r}\)
        return \((Q, L)\)
    \(j \leftarrow \max \left\{i \in\{1, \ldots, r\} \mid d_{i}>1\right\}\)
    \(\left(Q_{1}, \boldsymbol{L}_{1}\right) \leftarrow \operatorname{PADÉ}\left(d_{1}, \ldots, d_{j-1},\left\lfloor d_{j} / 2\right\rfloor, 1, \ldots, 1, \boldsymbol{G}, \leqslant, \boldsymbol{K}\right)\)
    \(G_{2} \leftarrow X_{j}^{-\left\lfloor d_{j} / 2\right\rfloor}\left(Q_{1} G \bmod X_{1}^{d_{1}}, \ldots, X_{j}^{d_{j}}, X_{j+1}, \ldots, X_{r}\right)\)
    \(\left(Q_{2}, L_{2}\right) \leftarrow \operatorname{PADÉ}\left(d_{1}, \ldots, d_{j-1},\left\lceil d_{j} / 2\right\rceil, 1, \ldots, 1, G_{2}, \preccurlyeq, L_{1}\right)\)
    \(Q \leftarrow Q_{2} Q_{1} \bmod X_{1}^{d_{1}+1}, \ldots, X_{r}^{d_{r}+1}\)
    return \(\left(Q, L_{2}\right)\)
```

The correctness of the algorithm can be shown by following the proof of Theorem 4.3 and with the following considerations. By
induction hypothesis, $Q_{1}$ is such that each component of the rows of $Q_{1} G$ is an element of

$$
\left\langle X_{1}^{d_{1}}, \ldots, X_{j-1}^{d_{j-1}}, X_{j}^{\left\lfloor d_{j} / 2\right\rfloor}, X_{j+1}, \ldots, X_{r}\right\rangle
$$

hence its truncation modulo

$$
\left\langle X_{1}^{d_{1}}, \ldots, X_{j}^{d_{j}}, X_{j+1}, \ldots, X_{r}\right\rangle
$$

is an $\mathcal{R}$-multiple of $X_{j}^{\left\lfloor d_{j} / 2\right\rfloor}$. It follows that on Line 11, $G_{2}$ is well defined. Moreover, for $\boldsymbol{p} \in \mathcal{R}^{m}$ the following equations are equivalent:

$$
\begin{aligned}
p Q_{1} G=0 & \bmod X_{1}^{d_{1}}, \ldots, X_{j-1}^{d_{j-1}}, X_{j}^{d_{j}} \\
p G_{2}=\boldsymbol{p} X_{j}^{-\left\lfloor d_{j} / 2\right\rfloor} Q_{1} G=0 & \bmod X_{1}^{d_{1}}, \ldots, X_{j-1}^{d_{j-1}}, X_{j}^{\left\lceil d_{j} / 2\right\rceil}
\end{aligned}
$$

This justifies the division by $X_{j}^{-\left\lfloor d_{j} / 2\right\rfloor}$ at Line 11 and the fact that the second call is done with $\left\lceil d_{j} / 2\right\rceil$ instead of $d_{j}$ at Line 12.

For the complexity analysis, we use Lemma 5.2 to give a bound on the size of the computed Gröbner bases which differs from the general bound in Lemma 4.2.

Corollary 5.4 (of Lemma 5.2). Let $\mathcal{N}$ be as in Eq. (6), let $\boldsymbol{F} \in$ $\mathcal{R}^{m \times n}$, let $\leqslant$ be a monomial order on $\mathcal{R}^{m}$, and let $\boldsymbol{P} \in \mathcal{R}^{k \times m}$ be a


$$
k \leq m d_{1} \cdots d_{r} /\left(\max _{1 \leq i \leq r} d_{i}\right)
$$

Proof. Let $L=\operatorname{lm}_{\S}(P) \in \mathcal{R}^{k \times m}$ and let $\bar{\imath}$ be such that $d_{\bar{\imath}}=$ $\max _{1 \leq i \leq r} d_{i}$. It is enough to prove that $L$ has at most $d_{1} \cdots d_{r} / d_{\bar{l}}$ rows of the form $\mu \boldsymbol{e}_{j}$ for each $j \in\{1, \ldots, m\}$; by Lemma 5.2 , the monomial $\mu \in \operatorname{Mon}(\mathcal{R})$ has $X_{i}$-degree at most $d_{i}$ for $1 \leq i \leq r$. Now, for each monomial $v=X_{1}^{e_{1}} \cdots X_{i-1}^{e_{i-1}} X_{i+1}^{e_{i+1}} \cdots X_{r}^{e_{r}}$ with $e_{i} \leq d_{i}$ for all $i \neq \bar{l}$, there is at most one row $\mu \boldsymbol{e}_{j}$ in $L$ such that $\mu=v X_{\bar{l}}^{e}$ for some $e \geq 0$ : otherwise, one of two such rows would divide the other, which would contradict the minimality of $P$. The number of such monomials $v$ is precisely $d_{1} \cdots d_{r} / d_{\bar{l}}$.

Here we have $D=n d_{1} \cdots d_{r}$, hence the above bound on the cardinality of minimal $\leqslant$-Gröbner bases refines the bound in Lemma 4.2 as soon as $m \leq n(r-1)\left(\max _{1 \leq i \leq r} d_{i}\right)$.

Proposition 5.5. For $\mathcal{R}=\mathbb{K}[X, Y]$, let

$$
\mathcal{N}=\left\langle X^{d}, Y^{e}\right\rangle \times \cdots \times\left\langle X^{d}, Y^{e}\right\rangle \subset \mathcal{R}^{n}
$$

let $\boldsymbol{F} \in \mathcal{R}^{m \times n}$ with $\operatorname{deg}_{X}(\boldsymbol{F})<d$ and $\operatorname{deg}_{Y}(\boldsymbol{F})<e$, and let $\leqslant$ be a monomial order on $\mathcal{R}^{m}$. Algorithm 4 computes a minimal $\leqslant-G r o ̈ b n e r ~$ basis of $\mathrm{Syz}_{\mathcal{N}}(F)$ using $\mathrm{O}^{\sim}\left(\left(M^{\omega-1}+M n\right)(M+n)\right.$ de) operations in $\mathbb{K}$, where $M=m \min (d, e)$.

Proof. According to Corollary 5.4, the number of rows of the matrices $Q$ computed in Algorithm 4 is at most $M=m \min (d, e)$. It follows that all matrices $Q_{i}, Q_{1}, Q_{2}, Q$ in the algorithm have at most $M$ rows and at most $M$ columns, and that the matrices $\boldsymbol{G}, \boldsymbol{H}, \boldsymbol{G}_{1}, \boldsymbol{G}_{2}$ have at most $M$ rows and exactly $n$ columns. Besides, by Kronecker substitution [7, Chap. 1 Sec. 8], multiplying two bivariate matrices of dimensions $M \times M($ resp. $M \times n)$ and bidegree at most $(d, e)$ costs $O^{\sim}\left(M^{\omega} d e\right)\left(\right.$ resp. $\left.O^{\sim}\left(M^{\omega}(1+n / M) d e\right)\right)$ operations in $\mathbb{K}$.

Let $C(m, n, d, e)$ denote the number of field operations used by Algorithm 4; we have $C(m, n, d, e) \leq C(M, n, d, e)$. First, for $e>1$, $C(M, n, d, e)$ is bounded by $C(M, n, d,\lfloor e / 2\rfloor)+C(M, n, d,\lceil e / 2\rceil)+$
$O^{\sim}\left(M^{\omega}(1+n / M) d e\right)$. Indeed, there are two recursive calls with parameters $(d,\lfloor e / 2\rfloor)$ and ( $d,\lceil e / 2\rceil$ ), and two matrix products $Q_{1} G$ and $Q_{2} Q_{1}$ to perform; as noted above, the latter products cost $O^{\sim}\left(M^{\omega}(1+n / M) d e\right)$ operations in $\mathbb{K}$. The same analysis for $d>1$ and $e=1$ shows that $C(M, n, d, 1)$ is bounded by $C(M, n,\lfloor d / 2\rfloor, 1)+$ $C(M, n,\lceil d / 2\rceil, 1)+O^{\sim}\left(M^{\omega}(1+n / M) d\right)$.

Finally, for $d=e=1$, we show that $C(M, n, 1,1) \in O(M(M+n) n)$. In this case, there are $n$ iterations of the loop. Each of them makes one call to Syzygy_BaseCase, which uses $O(M)$ field operations for computing the $\lambda_{i}$ 's at Line 7 ; note that the $\alpha_{j}$ 's are zero in the present context where the linear functional $\varphi$ corresponds to the constant coefficient. The computed basis $Q_{i}$ has a single nontrivial column (it has the form in Eq. (3)), so that computing $Q_{i} Q \bmod$ $\left\langle X_{1}^{2}, \ldots, X_{r}^{2}\right\rangle\left(\right.$ resp. $\left.Q_{i} H \bmod \left\langle X_{1}, \ldots, X_{r}\right\rangle\right)$ can be done naively at a cost of $O\left(M^{2}\right)($ resp. $O(M(M+n)))$ operations in $\mathbb{K}$.

Based on the previous inequalities, unrolling the recursion by following the divide-and-conquer scheme leads to the announced complexity bound.

## ACKNOWLEDGMENTS

Acknowledgements. The first author acknowledges support from the Fondation Mathématique Jacques Hadamard through the Programme PGMO, project number 2018-0061H.

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