Supplementary information

for the manuscript

CFD-guided patterning of tubular ceramic membrane surface by stereolithograhy: Optimizing morphology at the mesoscale for improved hydrodynamic control of membrane fouling

Cyril Chevarin¹, Xunhao Wang², Denis Bouyer^{1*}, Volodymyr V. Tarabara^{2**}, Thierry Chartier³, André Ayral¹

 ¹ Institut Européen des Membranes IEM – UMR 5635, ENSCM, CNRS, Univ Montpellier, Montpellier, France
 ² Department of Civil and Environmental Engineering, Michigan State University, East Lansing, MI 48824, USA
 ³ CNRS, University of Limoges, Institute of Research for Ceramics (IRCER), UMR 7315, European Ceramics Center, Limoges, France

S1. k- ε turbulence model

To take into account turbulence effect, the standard k- ε turbulence model [1] was used. This model is robust, accuracy and widely used for many flow applications.

In addition to the conservation of momentum equation in the Navier-Stokes equation (Eq. (1)), the standard k- ε turbulence model, which is a semi-empirical model, is based on two additional transport equations for the turbulent kinetic energy k and for the turbulent dissipation rate ε as follow:

For the turbulent kinetic energy k (in $m^2.s^{-2}$):

$$\rho(\vec{v}.\nabla k) = \nabla \left(\left(\eta + \frac{\eta_t}{\sigma_k} \right) \nabla k \right) + P_k - \rho \epsilon$$
(A1)

where P_k is the productive term of k due to the mean velocity gradients

$$P_k = \eta_t \left[\nabla \vec{v} : (\nabla \vec{v} + \nabla \vec{v}^T) - \frac{2}{3} (\nabla \cdot \vec{v})^2 \right] - \frac{2}{3} \rho k \nabla \cdot \vec{v}$$
(A2)

And for the turbulent dissipation rate ε (in m².s⁻³):

$$\rho(\vec{v}.\nabla\varepsilon) = \nabla \cdot \left(\left(\eta + \frac{\eta_t}{\sigma_{\varepsilon}} \right) \nabla \varepsilon \right) + C_{\varepsilon 1} \frac{\varepsilon}{k} P_k - C_{\varepsilon 1} \rho \frac{\varepsilon^2}{k}$$
(A3)

In this k- ϵ model, the turbulent viscosity , ((in m².s⁻²) was modeled by combining k and ϵ using the equation:

$$\eta_t = \rho C_\eta \frac{k^2}{\varepsilon} \tag{A4}$$

The standard k- ε model constants C_{ε_1} , C_{ε_2} , C_{η} , σ_k and σ_{ε} were issued from experimental data and could be adjusted. The default value of these constants are listed in Table S1.

| Table S1. | Model | constants. |
|-----------|-------|------------|
|-----------|-------|------------|

| Constant | C_{ε_1} | $C_{\varepsilon 2}$ | C_η | σ_k | $\sigma_{\mathcal{E}}$ |
|----------|---------------------|---------------------|----------|------------|------------------------|
| Value | 1.44 | 1.92 | 0.09 | 1.0 | 1.3 |

S2. Preparation of bacteria stock

To prepare the bacteria stock, one liter of PA01 (late exponential growth phase) with a final optical density (600 nm) of 1 were washed twice with 150 mM NaCl, (centrifuged for 10 min at 8000 rpm and 4 °C and resuspended by vortexing) and incubated in 4% formaldehyde solution for 2 h at room temperature to fix the bacteria. The cells were then washed three times with 150 mM NaCl (centrifuged for 10 min at 8000 rpm and 4 °C, and resuspended by vortexing) [20]. The fixed bacteria stock (pH 6) was stored at 4 °C for subsequent use.



Figure S1. Schematic of the crossflow filtration setup. Dead-end filtration tests were performed using the same system but with the retentate outlet closed.





Figure S2. Mapping of ε inside the tubular membrane for 3 distances between the rings (3, 4 and 5 mm) and the two explored values of v_{inlet} : (a) 0.45 m s⁻¹; (b) 0.68 m s⁻¹.



Figure S3. Evolution of fouling mechanism during dead-end filtration of bacterial suspensions by smooth and rough membranes.



dead-end filtration tests with smooth and rough membranes.

References

[1] B.E. Launder, D.B. Spalding, The numerical computation of turbulent flows, Comput. Method. Appl. Mechanics Eng., 3 (1974) 269-289.